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Author(s)	Yokoyama, Kazunori
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Continuity of ε -Approximate Solution Set

Kazunori Yokoyama (横山一憲) *

Abstract

In this note, we present the continuity of ε -approximate solutions set for the nonlinear programming problems. In [1], the similar continuity for the unconstrained problem was shown. We show another result. The continuity of the approximate solution set is estimated by using the ρ -distance.

1 Preliminaries

In this note, we consider the following nonlinear programming problem:

(P) minimize $f(x)$

subject to $g(x) \leq 0$

where $g = (g_1, \dots, g_m)$, f and $g_i (i = 1, \dots, m) : \mathbf{R}^n \rightarrow \mathbf{R}$.

We denote the feasible set $\{x \in \mathbf{R}^n \mid g(x) \leq 0\}$ by K .

We suppose that the following assumption is satisfied.

Assumption. Let f and $g_i (i = 1, \dots, m)$ be convex and f be bounded from below. Let $K \neq \emptyset$. The parameter ε is positive.

For the problem (P), the ε -approximate solution is well known as follows.

Definition 1.1. An element $\bar{x} \in K$ is said to be an ε -approximate solution for (P) if and only if \bar{x} satisfies that $f(x) + \varepsilon \geq f(\bar{x})$ for any $x \in K$.

We set $\inf_K f = \inf\{f(x) \mid x \in K\}$ and denote the ε -approximate solution set $\{\bar{x} \in K \mid f(x) + \varepsilon \geq f(\bar{x}) \text{ for any } x \in K\}$ by $A(\varepsilon)$.

Clearly, we have $A(\varepsilon) \neq \emptyset$ under the above assumption.

To estimate the approximate solution set, we define the ρ -distance and the Hausdorff distance:

*Department of Management and Information Sciences, Niigata University of Management, Kamo, Niigata, 959-13, Japan, e-mail address: kazu@duck.niigataum.ac.jp

Definition 1.2. For $C \subset \mathbf{R}^n$,

$$d(x, C) = \inf\{\|x - y\| \mid y \in C\}$$

denotes the distance from x to C . For any $C, D \subset \mathbf{R}^n, \rho \geq 0$, we set

$$C_\rho = C \cap \rho B$$

where $B = \{x \in \mathbf{R}^n \mid \|x\| \leq 1\}$: unit ball.

For, $\rho \geq 0$, the ρ -distance is defined to be

$$d_\rho(C, D) = \max\{e(C_\rho, D), e(D, C_\rho)\}$$

where $e(C, D) = \sup_{x \in C} d(x, D)$, and the Hausdorff distance between C and D is

$$haus(C, D) = \max\{e(C, D), e(D, C)\}.$$

2 The unconstrained case

In this section we introduce the result of [1]. In [1], Attouch and Wets investigated the Lipschitz continuity of the approximate solution set for the unconstrained programming problems. The problem is as follows:

minimize $F(x)$ where $F: \mathbf{R}^n \rightarrow \mathbf{R}$.

For this problem, the approximate solution set is defined to be

$$\varepsilon - \operatorname{argmin} F = \{\bar{x} \mid \inf F + \varepsilon \geq F(\bar{x})\}$$

where $\inf F = \inf\{F(x) \mid x \in \mathbf{R}^n\}$. Also, we denote level set of a function f by

$$\operatorname{lev}_\alpha F = \{x \in \mathbf{R}^n \mid F(x) \leq \alpha\}.$$

To show the Lipschitz continuity, the important lemma was proved in [1].

Lemma 2.1. [1, Lemma4.1.] Suppose that there exists $\rho_0 > 0$ such that

$$(\varepsilon - \operatorname{argmin} F)_{\rho_0} \neq \emptyset \text{ for all } \varepsilon > 0.$$

Then, for all $\alpha > \inf F$ and $\eta \geq 0$,

$$\text{for all } \hat{x} \in \operatorname{lev}_{(\alpha+\eta)} F, \quad d(\hat{x}, \operatorname{lev}_\alpha F) \leq \eta \frac{\|\hat{x}\| + \rho_0}{(\eta + \alpha) - \inf F}$$

which in turn implies that for all $\rho \geq \rho_0$,

$$d_\rho((\alpha + \eta) - \operatorname{argmin} F, \alpha - \operatorname{argmin} F) \leq \eta \frac{\rho_0 + \rho}{(\eta + \alpha) - \inf F}.$$

3 The constrained case

We apply lemma 2.1. to the constrained programming problems (P) .

Lemma 3.1. Suppose that there exists $\rho_o > 0$ such that

$$A(\varepsilon)_{\rho_o} \neq \emptyset \text{ for all } \varepsilon > 0.$$

Then, for all $\inf_K f + \varepsilon > \inf_K f$,

$$\text{for all } \hat{x} \in A(\varepsilon_2), d(\hat{x}, A(\varepsilon_1)) \leq (\varepsilon_2 - \varepsilon_1) \frac{\|\hat{x}\| + \rho_o}{\varepsilon_1}$$

which in turn implies that for all $\rho \geq \rho_o$,

$$d_\rho(A(\varepsilon_2), A(\varepsilon_1)) \leq (\varepsilon_2 - \varepsilon_1) \frac{\rho_o + \rho}{\varepsilon_1}.$$

However the above assumption does not hold in the following easy example.

Example 3.1. Let $f(x_1, x_2) = 2^{x_1+x_2}$:convex and $g(x_1, x_2) = (x_1, x_2)$:convex .
Then, we have

$$A(0) = \emptyset \text{ and } A(\varepsilon) = \{x \mid x \leq 0 \text{ and } 2^{x_1+x_2} \leq \varepsilon\}.$$

So, it holds

$$\|\bar{x}\| \rightarrow +\infty \text{ where } \bar{x} \in A(\varepsilon) \text{ as } \varepsilon \rightarrow 0.$$

We would like to change the assumption and show the similar result.

Proposition 3.1. We suppose that the strong Slater condition is satisfied.i.e. there are $x_s \in \mathbf{R}^n, \delta > 0$ such that

$$\delta \tilde{B} \subset H(x_s) + \mathbf{R}_+^{(m+1)}.$$

where $H(x) = (g(x), f(x) - \inf_K f - \varepsilon_1)$, $\tilde{B} \subset \mathbf{R}_+^{(m+1)}$: unitball.
Also, suppose there exists $C > 0$ such that

$$\sup_{x_0 \in A(\varepsilon_2) \setminus A(\varepsilon_1)} \|x_0 - x_s\| \leq C.$$

Then, we have

$$(A(\varepsilon_2), A(\varepsilon_1)) \leq \frac{(\varepsilon_2 - \varepsilon_1)C}{\delta}.$$

Remark. The assumption of proposition 3.1. is satisfied in example 3.1. Let $\varepsilon_2 = 0.5, \varepsilon_1 = 0.25$. So, there exist $x_s = (-2, -2)$ and $\delta = 0.125$ such that the strong Slater condition is satisfied. Since $A(\varepsilon_2) = \{x \mid x \leq 0, x_2 \leq -x_1 - 1\}, A(\varepsilon_1) = \{x \mid x \leq 0, x_2 \leq -x_1 - 2\}$, we have

$$\sup_{x_0 \in A(\varepsilon_2) \setminus A(\varepsilon_1)} \|x_0 - x_s\| \leq \|(-1, 0) - (-2, -2)\| = \sqrt{5} \text{ and } \text{haus}(A(0.5), A(0.25)) \leq \frac{(0.5-0.25)\sqrt{5}}{0.125}.$$

The above strong Slater condition is equivalent to the ordinary one.

Proposition 3.2. [9] The strong Slater condition is satisfied if and only if the Slater condition be done.

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